| INTEC |  |
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**MARVEL** 

|            | Marvel SPECIFICATIONS |                            |  |  |
|------------|-----------------------|----------------------------|--|--|
|            |                       | Channels                   | 1408   |  |
|            |                       |                            | GPS:L1C/A/L2P(Y)/L2C/L5  |  |
|            |                       |                            | GLONASS:L1/L2  |  |
|            |                       |                            | BDS:B1I/B2I/B3I/BIC/B2a/B2b                                    |  |
|            |                       | Satellites Tracking        | Galileo:E1/E5a/E5b/E6  |  |
|            |                       |                            | QZSS:L1/L2/L5/L6   |  |
|            | GNSS                  |                            | SBAS:L1  |  |
|            | Performance           | Positioning Rate           | Up to 50Hz   |  |
|            | , 0,,0,,,,,           | Operation System           | Linux  |  |
|            |                       | Initialization Time        | <5s(Typical value)   |  |
|            |                       | Initialization Reliability | 99.99%   |  |
|            |                       | Static Horizontal Accuracy | ±(2.5mmm+0,5x 10-6xD)  |  |
|            |                       | Static Vertical Accuracy   | ±(5mm+0.5x10-6xD)  |  |
|            |                       | RTK Horizontal Accuracy    | $\pm$ [8mm+1.0x10- $^6$ xD)                                    |  |
|            |                       | RTKVertical Accuracy       | ±(15mm+1.0xx10- <sup>6</sup> xD)                               |  |
|            |                       | IMU                        | Supported  |  |
| IMU Sensor | IMII Canaar           | Accuracy                   | Less than 2cm within 60°                                       |  |
|            | Tiltangle             | 0~120°                     |  |  |
|            |                       | Correction Data            | RTCM2.X, RTCM3.X   |  |
|            | Data Output           | GPS Data                   | NMEA 0183s RJK, Binary   |  |
|            |                       | Tilt Survey                | Supported  |  |
|            |                       | PPK Survey                 | Supported  |  |
|            | Function              | Buzzer                     | Supported  |  |
|            | Configuration         | Voice                      | Supported  |  |
|            |                       | NFC                        | Supported  |  |
|            |                       | Size                       | 120*89mm   |  |
|            |                       | Weight                     | 0.66kg   |  |
|            | Footon.               | Indicator Light            | Satellite + Data + Power + Bluetooth                           |  |
|            |                       | Operating Temperature      | -45℃~+75℃  |  |
|            |                       | Storage Temperature        | -55°C~+85°C  |  |
|            | Feature               | Water/Dust Proof           | IP67   |  |
|            |                       | Shock Resistance Grade     | Ik08   |  |
|            |                       | Shock                      | Survive a 1.8m drop  |  |
|            |                       | Static Data Format         | TXT  |  |
|            | Static Data           | Data storage               | 32G  |  |
|            | Recording             | Battery Capacity           | 7.4V, 7000mAh  |  |
|            |                       | Working Time               | 20 hours with rover CORS workmode                              |  |
| Electrical |                       | External Power             | 7.5 hours with base station work mode                          |  |
|            | Electrical            |                            | 1 x USB Type-C power, power bank supported                     |  |
|            |                       | I/OPort                    | 1 x USBType-C port (power supplyand charge)                    |  |
|            |                       | 1701 011                   | 1 x SMA radio antenna port                                     |  |
|            |                       | Wireless Communication     | 1 x Five-core Lemo port (9V-14V)                               |  |
|            |                       |                            | Supports Bluetooth. 4G handbook devices, WIFI, built in 4G-LTE |  |
|            |                       | Built In Network           |  |  |
| Commun     | ommunication          | Radio Transmit Power       | 2W   |  |
|            |                       | Standard Internal Rx/Tx    | 410-470 MHZ  |  |
|            |                       |                            | TRIMTALK450S, SATEL, TRIMMARKIII, TRANSEOT,                    |  |
|            |                       | Protocol                   | SOUTH, INTALK (LoRa)   |  |
|            |                       |                            | 5M&5M double high-definition cameras, with a large vie         |  |
|            | Camera                | Function                   | wing angle that supports real-life AR stakeout                 |  |
| 1          | aser Tilt Survey      | Laser Survey               | Supported. Three-D error: 0.008+0.005*D (tiltangle s30)        |  |
| -          | acci intourvey        | Laser Survey               | Capported. Three Berrot. C.000 C.000 B (thrange 500)           |  |







## Millimeter Level Laser Professional Camera Better Real Stakeout

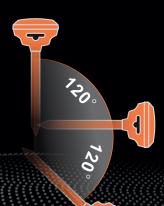
- \*Realistic stakeout, with clear and precise stakeout points; overlay design files, combining virtual and real points clearly, greatly improving the efficiengy of stakeout.
- \*Professional starlight night vision HD lens with wide viewing angle, combined with professional algorithms, with accuracy better than lcm.
- \*Carefully selected 3R class green light, clearly visible under strong light, with millimeter level laser module embedded at the back.
- \*360 ° panoramic measurement brings you a different work experience. Point to point pile measurement, laser pointing, and measurement reach, challenging complex environment and mastering the field of measurement.



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## New Generation High-precision IMU Automatic Initialization Upon Startup

- \* Newly upgraded seamless super IMU, 120° large angle without initialization, bidding farewell to shaking.
- \* After initialization is complete, there is no need to exit. The inertial navigation can be used whenever the receiver is shoulder resistant, hand-held, or horizontally placed.
- \* No need to look at the bubbles, point to measure, with reliable accuracy.





- \*Self-developed PPP-IAR algorithm can achieve high-precision operations even in areas without communication networks, as well as in mountainous, oceanic and desert areas where CORS network signals are not covered.
- \*High performance RTK core, integrated with developed algorithm, combined with high-density CORS nationwide, to achieve fixed startup seconds; according to the working environment, the host automatically selects the optimal algorithm, which can maintain a fixed solution and stable accuracy even when the ionosphere is active.
- \*Even if the signal is interrupted, it can still maintain cm level accuracy and continue working over 5 minutes, focusing on solving pain points such as weak and unstable signals in forest areas and cross regional boundaries, greatly improving the availability of RTK.



## Power Indicator light Bulit-in 2W radio with

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- \*With the power indicator light, we can effectively control the usage time of the receiver, thereby improving work efficiency
- \*With built-in 2W radio with lora protocol, the working distance of the radio can reach over 15 km, effectively improving the efficiency of the surveyor's work

